



- (b) Explain the speed torque characteristic of a **dc** shunt motor.
- (c) Explain commutation in **DC** generator.
- (d) Explain the field flux control method for speed control of a **dc** shunt motor.
- (e) A **4** pole dc shunt motor working on **250V** takes a current of **2A** when running at no load at **1000 rpm**. How much back emf is generated? What will be its back emf, speed and percentage speed drop if the motor takes **51A** at a certain load? Armature resistance and shunt field resistance are **0.2  $\Omega$**  and **250  $\Omega$**  respectively.
- (f) A **6** pole, lap connected with **864** conductors dc motor takes an armature current of **110A** at **480V**. The armature circuit has a resistance of **0.2  $\Omega$** . The flux per pole is **0.05 wb**. Calculate :
  - (i) The speed and
  - (ii) The gross torque developed by the armature.

**3** Attempt any **four** parts of the following : **5 $\times$ 4=20**

- (a) Explain the principle of working of three phase induction motor.
- (b) Discuss the constructional differences between a squirrel cage and wound rotor induction motor.
- (c) Draw the power flow diagram of a three phase induction motor.
- (d) Explain the effect of change of excitation of a synchronous motor on its armature current and its power factor.

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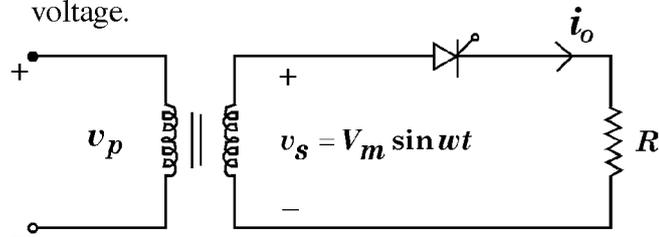
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- (e) Draw and explain the phasor diagram of synchronous motor operating at lagging power factor.
- (f) A **37.3 kW**, **4 pole 50 Hz** induction motor has friction and windage losses of **3.32 kW**. The stator losses equal the rotor losses. If the motor is delivering full load power output at a speed of **1440 rpm**, calculate synchronous speed, slip, mechanical power developed by the motor and rotor copper loss.

**4** Attempt any **four** parts of the following : **5×4=20**

- (a) The reverse recovery time of a diode is  $t_{rr} = 3 \mu s$  and the rate of fall of the diode current is  $di/dt = 30 A/\mu s$ . Determine :
- the storage charge  $Q_{RR}$  and
  - the peak reverse current  $J_{RR}$ .
- (b) For the single phase thyristor converter shown in **Fig 1**, derive the expression for rms output voltage.



- (c) For a single phase semiconverter, sketch waveforms for load voltage and load current for :
- RL load
  - RL load with free wheeling diode across RL. Indicate clearly the conduction period of the devices.

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- (d) A single phase full converter feeds power to **RLE** load with  **$R = 6 \Omega$** ,  **$L = 6 \text{ mH}$**  and  **$E=60 \text{ V}$** . The **ac** source voltage is **230V**, **50 Hz**. For continuous conduction, find the average value of load current for a firing angle delay of **50°**.

If one of the four thyristors gets open circuited, find the new value of average load current taking the output current as continuous.

- (e) Discuss the advantages and disadvantages of circulating current in a single phase dual converter.
- (f) Draw the circuit diagram and output voltage waveforms of a single phase cycloconverter.

**5** Attempt any **two** parts of the following : **10×2=20**

- (a) What is duty cycle in chopper control circuit? Explain the operation of a step-up chopper circuit.
- (b) Describe the operation of a three phase **180°** mode voltage source inverter and draw its voltage waveforms.
- (c) What are the different techniques for the control of voltage of an inverter? Explain the sinusoidal pulse width modulation technique.