

(Following Paper ID and Roll No. to be filled in your Answer Book)

**PAPER ID : 131604**

Roll No.

--	--	--	--	--	--	--	--	--	--

**B.Tech.**

(SEM. VI) THEORY EXAMINATION 2013-14

**INTRODUCTION TO ELECTRIC DRIVES**

*Time : 2 Hours*

*Total Marks : 50*

**Note :** Attempt **all** questions. All questions carry equal marks.

1. Attempt any **two** parts of the following : **(5×2=10)**
  - (a) Explain why the inner two layers of an SCR are lightly doped & wide
  - (b) What is meant by commutation of SCR ? What are the different types of forced commutation methods ?
  - (c) Draw the turn-off characteristics of an SCR & explain its mechanism.
2. Attempt any **two** parts of the following : **(5×2=10)**
  - (a) Explain the operation of a three-phase, half controlled bridge converter with suitable waveform.
  - (b) A three phase half-wave controlled rectifier has a supply of 200 V/ phase. Determine the average load voltage for firing angle of  $0^\circ$  &  $60^\circ$ , assuming a thyristor voltage drop of 1.5 V & continuous load current.
  - (c) Justify the statement "free wheeling diode improves the power factor of the system."
  - (d) Explain the operation of single-phase bridge inverter with the help of load voltage & load current wave form.

3. Attempt any **two** parts of the following : **(5×2=10)**
- (a) Explain the principle of chopper operation what are the types of control strategies in chopper ? Explain any of them.
  - (b) A chopper circuit is operating on TRC principle at a frequency of 2 KHz on a 220 V dc supply. If the load voltage is 170 V, compute the conduction of blocking period of thyristor in each cycle.
  - (c) Why does a three phase to single phase cycloconverter required positive & negative group phase controlled converter ? Explain.
4. Attempt any **two** parts of the following : **(5×2=10)**
- (a) Explain in brief any one method of braking of a dc motor.
  - (b) Draw & explain the torque-speed characteristics of a separately excited dc motor at different firing angles for a full converter feeding.
  - (c) Explain with the associated wave form, how power factor can be improved with symmetrical angle control scheme.
5. Attempt any **two** parts of the following : **(5×2=10)**
- (a) Explain the variable frequency control method of an induction motor. Also explain operation below the rated frequency mode.
  - (b) An inverter supplies a 4-pole, three phase cage induction motor rated at 220 V, 50 Hz. Determine the approximate output required of the inverter for motor speed of :  
(i) 900 (ii) 1200 (iii) 1500 (iv) 1800 rpm.
  - (c) Draw a suitable diagram & explain working of slip power recovery system using commutator-less Kramer drive.